

Student Data

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| Student Name (last, first MI) | | Training Date | |
| Gaining Company/Agency | | Model | |
| Email Address | | Primary Phone | |
| Mailing Address | | | |

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| 1. Introduction Segment | | + | = | - |
| General Requirements | | | | |
| 2. Information Segment | | + | = | - |
| 2.1 | Identify and summarize the WARNING DECALS posted on the SPYDERCRANE | | | |
| 2.4 | Point out and identify the TRAVEL LIMIT INFORMATION DECALS on the SPYDERCRANE | | | |
| 2.5 | Point out and identify the SLING INFORMATION DECALS on the SPYDERCRANE | | | |
| 2.6 | Point out and identify the PRIMARY/SECONDARY POWER-PLANT INFORMATION DECALS on the SPYDERCRANE | | | |
| 2.7 | Point out and identify the OUTRIGGER DEPLOYMENT INFORMATIONAL DECALS on the carrier of the SPYDERCRANE | | | |
| 2.14 | Explain where to find information on interpreting CMU CODES | | | |
| 2.15 | Explain where to find information on using the LOAD MOMENT INDICATOR (LMI) | | | |
| General Requirements | | | | |
| 3. Travel Segment | | + | = | - |
| 3.4 | Explain the TRAVEL LIMITS of the SPYDERCRANE | | | |
| 3.6 | Demonstrate starting and changing the MODE OF OPERATION of the SPYDERCRANE | | | |
| 3.7 | Demonstrate using the ACCELERATOR and HIGH-SPEED MODE BUTTON when traveling the SPYDERCRANE | | | |
| 3.8 | Demonstrate identifying and compensating for the stowed-boom blind-spot of the SPYDERCRANE when in Travel Mode | | | |
| General Requirements | | | | |
| 4. Daily Inspection Segment | | + | = | - |
| 4.1 | Demonstrate how to start the SPYDERCRANE DAILY INSPECTION | | | |
| 5. Deploy Segment | | + | = | - |
| 5.2 | Demonstrate, or explain, using OUTRIGGER PADS when deploying the SPYDERCRANE | | | |
| 5.3 | Properly define MAX-EXT , MID-EXT , and NOT-EXT DEPLOYMENT STATES | | | |
| 5.4 | Demonstrate PRE-DEPLOYING the SPYDERCRANE | | | |
| 5.5 | Demonstrate PRE-DEPLOYING the SPYDERCRANE. | | | |
| 5.7 | Demonstrate DEPLOYING the SPYDERCRANE using the OUTRIGGER CONTROL GROUP (OCG) | | | |
| 5.8 | Demonstrate maintaining situational awareness of the moving outriggers | | | |
| 5.9 | Demonstrate LEVELING the SPYDERCRANE within 1° and visually confirming that all outriggers are GROUNDING and the tracks are CLEAR | | | |
| General Requirements | | | | |
| 6. Lift Inspection and Test Segment | | + | = | - |
| 6.1 | Demonstrate how to start the SPYDERCRANE LIFT INSPECTION | | | |
| 6.2 | Explain the function of the ANTI-TWO BLOCK (A2B) SYSTEM and the BOOM A2B SWITCH | | | |
| 6.3 | Explain the function of the BOOM STOW SAFETY | | | |
| 6.4 | Explain the function and describe the operations display of the LMI | | | |
| 6.5 | Explain the function of the MINIMUM WIRE ROPE SAFETY | | | |
| 6.6 | Describe how inspect the WIRE ROPE for damage | | | |
| 6.7 | Describe the damage/excessive wear indicators for WIRE ROPE | | | |
| General Requirements | | | | |

| 7. Crane Control Segment | | + | = | - |
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| 7.1 | Demonstrate setting up the LMI | | | |
| 7.2 | Demonstrate the UNSTOWING THE HOOK AND BOOM PROCEDURE | | | |
| 7.3 | Demonstrate using the CRANE CONTROL GROUP (CCG) to safely control the upperworks of the SPYDERCRANE | | | |
| 7.4 | Demonstrate HOOK STORE (CCG) | | | |
| 7.7 | Demonstrate the proper HOOK GROUNDING PROCEDURE | | | |
| 7.8 | Demonstrate the proper procedure for LIFTING A GROUNDED HOOK | | | |
| 7.9 | Demonstrate identifying the EMERGENCY STOP (E-STOP) | | | |
| 7.10 | Demonstrate the proper procedure for STOWING THE HOOK AND BOOM | | | |
| 7.18 | Explain the difference between the EMERGENCY STOP and the REMOTE EMERGENCY STOP | | | |
| General Requirements | | | | |
| 8. Safe Lifting Segment | | + | = | - |
| 8.1 | Demonstrate the ability to maintain the same LIFTING HEIGHT while changing the WORKING RADIUS | | | |
| 8.2 | Demonstrate safely executing THE PICK | | | |
| 8.3 | Demonstrate moving a load while minimizing LOAD SWING | | | |
| 8.4 | Demonstrate how to increase SPYDERCRANE STABILITY while MOVING a load | | | |
| 8.5 | Demonstrate the proper technique for changing WORKING RADIUS while MOVING a load | | | |
| 8.6 | Demonstrate SITUATIONAL AWARENESS while CONTROLLING A LIFT | | | |
| 8.7 | Demonstrate controlling a load during THE DROP | | | |
| 8.8 | Demonstrate using the RATED LOAD CHART (BOOM) | | | |
| 8.9 | Explain RATED LOAD CAPACITY and NET-RATED LOAD CAPACITY | | | |
| 8.10 | Demonstrate properly DEDUCTING hook and rope weight for NET-RATED LOAD CAPACITY for the 4-PART HOOK | | | |
| 8.11 | Demonstrate properly DEDUCTING hook and rope weight for NET-RATED LOAD CAPACITY for the 1-PART HOOK (BOOM) | | | |
| 8.12 | Demonstrate calculating RATED LOAD CAPACITY , based on the SPYDERCRANE's DEPLOYMENT STATE | | | |
| 8.13 | Demonstrate the ability to measure WORKING RADIUS | | | |
| General Requirements | | | | |
| 10. Primary/Secondary Power-Plant Segment | | + | = | - |
| General Requirements | | | | |

Notes and Comments**Instructor**